#### Specifications

Oþ	ecifications		Model	
Ite	n		Multitask Platform <b>JM-10</b>	
	Board size			Min.50×50~Max.410×250mm
ing	Component height			28mm (component body 25mm + lead length 3mm)
onut	Component size	Laser recognition		0603 (0201)∼□33.5mm
ž	Placement speed	Pickup nozzle(Optimum)**1		0.8 sec./component
Insertion Mounting		Gripper nozzle(Optimum) <sup>ж1</sup>		1.3 sec./component
	Number of component to be attached	Bowl Feeder		12 types max
		Radial Feeder		20 types max
	Board size			Min.50×50~Max.410×250mm
	Component height			25mm
	Component size	Laser recognition		0603 (0201)∼□33.5mm
ting		Vision recognition(option)	54mm view camera**2	□3mm~33.5mm
onu			27mm view camera**2	1.0×0.5mm~□24mm
Surface Mounting	Placement speed	Chip	(Optimum)	17,500CPH
			(IPC9850)	12,500CPH
		IC		4,100CPH**3
	Placement accuracy	Laser recognition		±0.05mm (±3σ)
		Vision recognition (option)		±0.04mm
	Number of component to be attached			Max.60 in case of 8mm tape
Po	wer supply			200 to 415 VAC,3-phase
Apparent power				1.8kVA
Ор	erating air pressure		0.5±0.05Mpa	
Air	consumption		345L/min (Opt: Vacuum Pump 50L/min)	
Ма	chine dimensions (W×D×H) <sup>#4</sup>		1,455×1,295×1,460mm	
Ма	ss (approximately)		1,000kg	

- \*1 Placement rate will vary by component type. Please consult your representative for more information.

  \*2 Upward looking component centering camera is optional. Choose from either a 54 or 27mm field of view.

  \*3 Estimated value when using Vision centering system, Simultaneous pick up for components 10mm or smaller QFP or BGA by all nozzles.

  \*4 Dimensions of machine described are for conveyor height 900mm.

#### **Options**

for Insertion Mounting	Component handling and feeders	Bowl Feeder (MBF) / Radial Feeder (MRF) / Table for radial components	
	Conveyor	Handle arm (for MBF)*1	
for Surface Mounting	Recognition system	Vision centering system <sup>#2</sup> (54mm view camera, 27mm view camera)	
	Safety device Feeder floating detecting sensor (Front) / Feeder floating detecting sensor (Rear)		
	Others	Residual number-of-components control	
	Component handling and feeders	Tape feeder 8~72mm / Bulk feeder / Stick feeder / Feeder stocker / Connector gig for tape	
for Insertion Mounting and	Conveyor	Conveyor extension guide / Conveyor height 950mm	
Surface Mounting	Safety device	Ground-fault interrupter	
	Others	Caster / Vacuum pump / Main line filter / Quick connect coupling / Three-color signal light (with buzzer) /	
		DVD , CD-ROM drive (USB) / FD drive (USB) / ATC 6-6	
	Software	EPU	
	Component handling and feeders	Tray Holder / Tape reel mounting base (for Tape Feeder,MRF)	

- \*1 This is a handle for adjusting the PWB width. This handle arm is used when a bowl feeder is installed on the right side of the bank or two bowl feeders are installed.
- \*2 Upward looking component centering camera is optional. Choose from either a 54 or 27mm field of view.
- \*Please refer to the product specifications for details.





#### **JUKI CORPORATION**

Electronic Assembly Systems Business Unit MIB Promote Division

2-11-1, Tsurumaki, Tama-shi, Tokyo 206-8551, JAPAN TEL.81-42-357-2321 FAX.81-42-357-2297

JUKI Specifications and appearance may be changed without notice.

### http://www.juki.co.jp

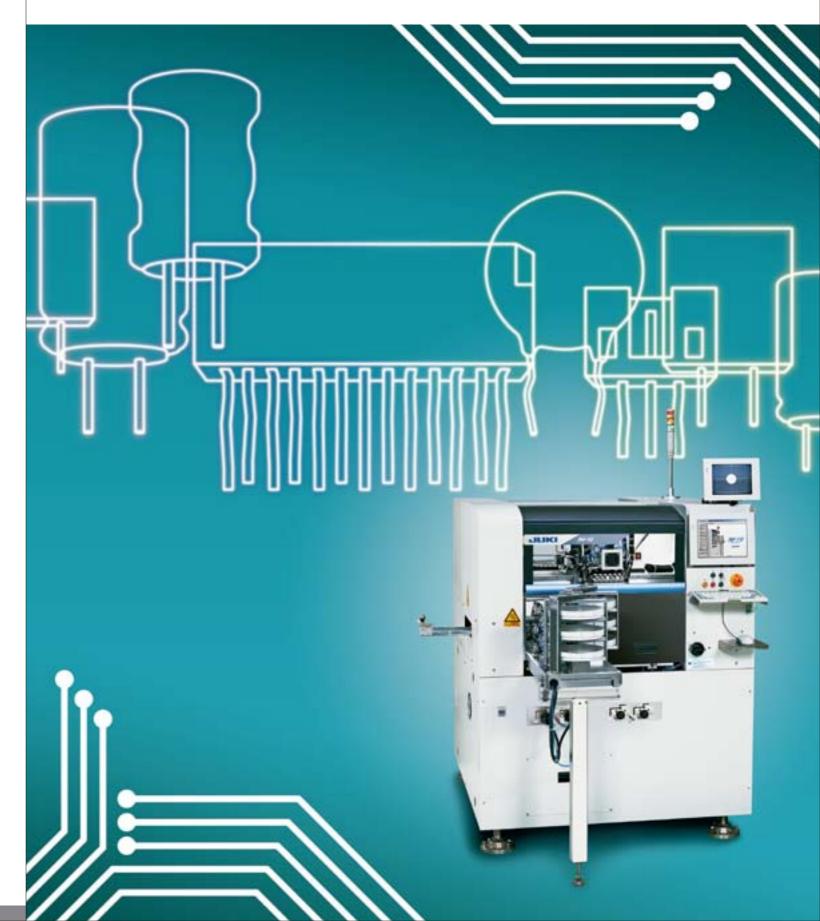
Jan-2012/0000/Rev.00



# JM-10







# Introducing the JM-10, the world's first multi-task platform.

The JM-10 is a revolutionary new concept from JUKI that allows for the placement or insertion of both surface mount

and through-hole components.

**Multitask Platform** 

JM-10

Surface Mounting Insertion Mounting



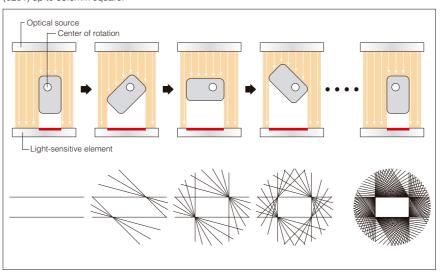
# JM-10 has the widest component range in the electronics industry. **Surface Mount Technology Manual Insertion Auto Insertion Multitask Platform** JM-10 MELF PLCC AL CN Radial lead Connector, Capacitor, Chip, SOP, BGA etc. components etc. Inductor etc.

### JUKI's revolutionary technology adds through-hole placement along with conventional SMT.

#### Laser centering technology (Laser sensor: LNC60)

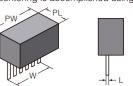
#### Component centering using laser

Components are rotated 360 degrees in the laser. The entire outline of the component is measured accurately by a high resolution CCD sensor. The exact component position and angle are obtained in a fraction of a second without a side trip to a camera. Laser recognition can be performed from 0603 (0201) up to 33.5mm square.



#### Simplified Data Entry

Simple data entry and fast, accurate lead-based component centering is accomplished using Laser Align.



#### Recognition of leads utilizing laser recognition

Using laser recognition, it will be possible to precisely recognize the lead parts to realize accurate insertion of pin insertion components



#### Component handling and feeders

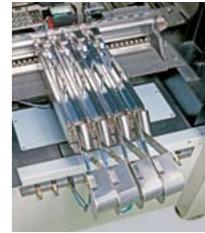
#### ● Bowl Feeder(MBF)



Vibratory bowl feeders are available for bulk components. Each feeder can hold up to six different components.

wo feeders can be mounted on each machine for a maximum of 12 different bulk components.

#### Radial Feeder(MRF)



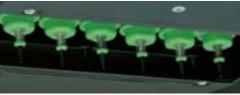
or taped components, radia eeders are available

The radial feeder cuts the leads and presents the components accurately for pick up.

Up to 10 feeders can be mounted both on the front and rear sides of the JM-10.

#### Standard equipped with 6 nozzles

The standard placement head has 6 nozzles and laser centering. A variety of common nozzle types also are included, and a vast assortment of specialized and custom nozzles are available for unusual components. Please consult your local JUKI representative regarding the production of special order nozzles to match components.





## Compact and less weight

